

Introduction to Superconductivity

Chapter 4 The Critical Magnetic Field

 $\sqrt{2}$ Å

Magnetism Electrostatics

 $d\mathbf{F} = id\mathbf{l} \times \mathbf{B}$ $d\mathbf{F} = dq \cdot \mathbf{E}$

$$
d\mathbf{B} = \frac{\mu_0}{4\pi r^2} id\mathbf{l} \times \hat{\mathbf{r}} \quad \textbf{Biot-Savart Law} \qquad \qquad d\mathbf{E} =
$$

$$
d\mathbf{E} = \frac{dq}{4\pi\varepsilon_0 r^2} \mathbf{\hat{r}}
$$

B is the basic magnetic quantity!

Ampere circuital Law

$$
\oint \mathbf{B} \bullet d\mathbf{l} = \mu_0 i
$$

Magnetic flux density inside an infinite long solenoid

$$
Bx = u_0 Ni
$$

$$
\Rightarrow \boxed{B = u_0mi}
$$

 $m = N/x$ turns per unit length *mi* : *units*(*A/m*)

 \mathcal{X} ! **turns enclosed by the closed red path**

 $\mathbf{B} = \mu_0 m \mathbf{i} + \mu_0 \mathbf{M}$

Define a new vector

 $H = m\mathbf{i}$

The magnetic field strength Does not depend on M

Total Flux density

$$
\mathbf{B} = \frac{\mathbf{B} - \mathbf{B} - \math
$$

 \times \times \times \times \times

$$
\mathbf{B} = \mu_0 \mathbf{H} + \mu_0 \mathbf{M}
$$

\n
$$
\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 (mix + Mx) = \mu_0 (i_f + i_M)
$$

\nFree current

In small magnetic fields:

$$
\mathbf{M}=\chi\mathbf{H}
$$

 χ is the magnetic susceptibility

$$
\Rightarrow \mathbf{B} = \mu_0(\mathbf{H} + M) = \mu_0(1 + \chi)\mathbf{H} = \mu_0\mu_r\mathbf{H}
$$

 $\mu_r = 1 + \chi$ is the relative permeability

For superconductors:

$$
B = 0 \Rightarrow \begin{cases} M = -H \\ \chi = -1 \end{cases}
$$

 $T < T_C$ $B = 0$ χ *T* T_c −1

Maxwell equation

 $\nabla \cdot \mathbf{H} = - \nabla \cdot \mathbf{M}$

 \boldsymbol{M}

$$
\nabla \cdot \mathbf{B} = \nabla \cdot (\mathbf{H} + \mathbf{M}) = 0
$$

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 H_d

• **H is not divergence free**

• **H behaves as if magnetic monopoles exist.**

The internal field and flux density are:

$$
\mathbf{H}_{i} = \mathbf{H}_{a} + \mathbf{H}_{d} \quad \mathbf{B} = \mu_{0} (\mathbf{H}_{i} + \mathbf{M})
$$

= $\mathbf{H}_{a} - N\mathbf{M} \quad = \mu_{0} (\mathbf{H}_{a} - N\mathbf{M} + \mathbf{M})$
= $m\mathbf{i} - N\mathbf{M}$

For superconductor:

$$
\mathbf{M} = -\mathbf{H} \qquad \mathbf{H}_i = \left(\frac{1}{1-N}\right)\mathbf{H}_a
$$

Demagnetization effect

Demagnetization Effect

For an ellipsoidal:
$$
\mathbf{H}_d = -N\mathbf{M}
$$

Demagnetization Effect

In general

 \mathcal{C}

$$
(H_d)_i = -\sum_j N_{ij} M_j
$$

M along the principal axes

$$
N = \left(\begin{array}{ccc} N_x & 0 & 0 \\ 0 & N_y & 0 \\ 0 & 0 & N_z \end{array}\right)
$$

For a sphere

$$
N_x = N_y = N_z = 1/3
$$

For a long cylinder

$$
N_x = N_y = 1/2, N_z = 0
$$

Boundary Conditions

Magnetic induction/Magnetic flux density (B) = Magnetic flux per unit area. Units: [Tesla = Weber/m² = Vs/m² = Kg/s²/A] Magnetization (M) = magnetic moment (m) per unit volume (V). Units: [A/m] $M = m/V$ Magnetic field strength/Magnetizing force (**H**). Units: [A/m]

Magnetic susceptibility (χ). (volume susceptibility) Units: [dimensionless] $\chi = M/H$

Magnetic units

温度 T *H^c* **Critical magnetic field strength**

Superconductor loose superconductivity when the applied magnetic field is larger than a certain critical value.

Critical current density *Jc*

The Critical Magnetic Field

 $\sqrt{2}$ Å

Phase diagram-相图

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Application- Cryotron

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Reversible Magnetization for ideal specimens

Magnetization

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Irreversible Magnetization for non-ideal specimens

Magnetization

Measurement of flux density

Measurement of magnetization